#### Modelling hypoxia in the Hamilton Harbour, Ontario, Canada: A Bayesian approach

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#### **Hamilton Harbour**





## Water quality standards TP loading $\leq 142 \text{ kg day}^{-1}$ Total Phosphorus $\leq 17$ (or 20) $\mu g L^{-1}$ Chlorophyll $a \leq 5-10 \ \mu g \ L^{-1}$ Secchi disk depth $\geq 3 m$ $DO \geq 4 mg L^{-1}$



## Probabilistic projection of system response to nutrient loading reduction strategies



# Chlorophyll a predictive distributions for different levels of Total Phosphorus



### **Objectives**

- How possible is it to meet the *DO* delisting objective, if the nutrient loading reductions proposed by the Hamilton Harbour Remedial Action Plan are actually implemented?
- What additional remedial actions are needed to increase the likelihood of meeting the DO target?
  What are the major sources of uncertainty that will ultimately determine the attainment of the existing delisting goal?

#### **Spatial Segmentation**



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#### **Bayesian Approach**

#### In modeling context:





#### **Bayesian DO modelling**



**Model structural error** 

#### **Bayesian DO modelling**

$$P(p(\delta_t | \delta_{-t}, \omega^2) \sim \begin{cases} N(2\delta_{t+1} - \delta_{t+2}, \omega^2) & \text{for } t = 1 \\ (2\delta_{t+1}, \omega^2) \text{for } t = 1 \\ N(\delta_{t+1}, \omega^2) \text{for } t = 1 \\ N\left(\frac{\delta_{t-1} + \delta_{t+1}}{2}, \frac{\omega^2}{2}\right) \text{for } t = 2, ..., T - 1 \\ N(\delta_{t-1}, \omega^2) \text{for } t = T \\ (\delta_{t-1}, \omega^2) \text{for } t = T \\ N(\delta_{t-2} - 2\delta_{t-1}, \omega^2) & \text{for } t = T \end{cases}$$

**Conditional autoregressive term to accommodate the serial correlation of the daily data** 





### **Bayesian Kriging**

multivariate Gaussian distribution with covariance matrix expressed as a parametric function of distance between pairs of points

$$f(d_{xy};\phi,\kappa) = \exp[-(\phi \cdot d_{xy})^{\kappa}]$$

 $d_{xy}$  represents the distance between the different pairs of grid cells  $\phi$  controls the rate of decline of correlation with distance

κ controls the amount by which spatial variations in the data are smoothed.

#### **DO prediction**



Jan Feb Mar Apr May Jun Jul Aug Sep Oct Nov Dec Jan

#### **DO prediction (Jun. to Sep.)**



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#### DO violations (<4 mg L<sup>-1</sup> Jun. to Sep.)



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#### Advantages of our Bayesian Emulator

- Flexible structure with low computational demands (1/200 of the typical computational time of 3-D hydrodynamic models);
- Explicit consideration of all the sources of uncertainty (structural, parametric, natural variability);
- Methodological tool that can be augmented by increasing the fidelity of the hydrodynamic component;
- •Ability to sequentially update beliefs as new knowledge is available, and the consistency with the scientific process of progressive learning and the policy practice of adaptive management.

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